

A magnetic head position controller in a magnetic recording and reproducing apparatus

Patent number: EP0509545
Publication date: 1992-10-21
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Classification:
- international: G11B5/588
- european: G11B5/588
Application number: EP19920106760 19920421
Priority number(s): JP19920028526 19920214; JP19910088573 19910419;
JP19910171064 19910711; JP19910221895 19910902

Also published as:



US5384676 (A)
EP0509545 (A)
EP0509545 (B)

Cited documents:



EP0361381
JP12053881

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Abstract of EP0509545

In a magnetic recording and reproducing apparatus having a solenoid-driven actuator to move a magnet head in the tracking direction, a magnetic head position controller comprises: a state estimator for estimating the moving speed of the actuator from a drive voltage and a drive current supplied to the actuator; and a damping control loop for feeding back the estimated speed signal estimated by the state estimator to the actuator drive voltage. The state estimator is formed of a combination of equivalent circuits that electrically simulate modeled characteristics of the solenoid-driven actuator, and the state estimator takes in the drive voltage and the drive current for the actuator and produces the estimated speed signal representing the speed of the actuator. The state estimator includes equivalent circuits that electrically simulate a drive coil resistance and inductance characteristic of the solenoid-driven actuator, force constant of the magnetic circuit, an inertia, a spring constant, and a counter electromotive force.

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